Real-Time Linux with *PREEMPT_RT* training
On-line seminar, 3 sessions of 4 hours
Latest update: May 08, 2024

Title	**Real-Time Linux with *PREEMPT_RT* training**
Training objectives	• Be able to understand the characteristics of a real-time operating system • Be able to download, build and use the *PREEMPT_RT* patch • Be able to identify and benchmark the hardware platform in terms of real-time characteristics • Be able to configure the Linux kernel for deterministic behavior. • Be able to develop, trace and debug real-time user-space Linux applications.
Duration	**Three** half days - 12 hours (4 hours per half day)
Pedagogics	• Lectures delivered by the trainer, over video-conference. Participants can ask questions at any time. • Practical demonstrations done by the trainer, based on practical labs, over video-conference. Participants can ask questions at any time. Optionally, participants who have access to the hardware accessories can reproduce the practical labs by themselves. • Instant messaging for questions between sessions (replies under 24h, outside of week-ends and bank holidays). • Electronic copies of presentations, lab instructions and data files. They are freely available at https://bootlin.com/doc/training/preempt-rt.
Trainer	Maxime Chevallier `https://bootlin.com/company/staff/maxime-chevallier/`
Language	Oral lectures: English, French. Materials: English.
Audience	Companies and engineers interested in writing and benchmarking real-time applications and drivers on an embedded Linux system.

Prerequisites	• **Knowledge and practice of UNIX or GNU/Linux commands**: participants must be familiar with the Linux command line. Participants lacking experience on this topic should get trained by themselves, for example with our freely available on-line slides at bootlin.com/blog/command-line/. • **Minimal experience in embedded Linux development**: participants should have a minimal understanding of the architecture of embedded Linux systems: role of the Linux kernel vs. user-space, development of Linux user-space applications in C. Following Bootlin's *Embedded Linux* course at bootlin.com/training/embedded-linux/ allows to fulfill this pre-requisite. • **Minimal English language level: B1**, according to the *Common European Framework of References for Languages*, for our sessions in English. See bootlin.com/pub/training/cefr-grid.pdf for self-evaluation.
Required equipment	• Computer with the operating system of your choice, with the Google Chrome or Chromium browser for videoconferencing. • Webcam and microphone (preferably from an audio headset) • High speed access to the Internet
Certificate	Only the participants who have attended all training sessions, and who have scored over 50% of correct answers at the final evaluation will receive a training certificate from Bootlin.
Disabilities	Participants with disabilities who have special needs are invited to contact us at *training@bootlin.com* to discuss adaptations to the training course.

Hardware platform for practical labs

STMicroelectronics STM32MP157D Discovery Kit 1 board
- STM32MP157D (dual Cortex-A7) processor from STMicroelectronics
- USB powered
- 512 MB DDR3L RAM
- Gigabit Ethernet port
- 4 USB 2.0 host ports
- 1 USB-C OTG port
- 1 Micro SD slot
- On-board ST-LINK/V2-1 debugger
- Arduino compatible headers
- Audio codec, buttons, LEDs

Half day 1

Lecture - Introduction to Real-Time behaviour and determinism

- Definition of a Real-Time Operating System
- Specificities of multi-task systems
- Common locking and prioritizing patterns
- Overview of existing Real-Time Operating Systems
- Approaches to bring Real-Time capabilities to Linux

Lecture - The *PREEMPT_RT* patch

- History and future of the *PREEMPT_RT* patch
- Real-Time improvements from *PREEMPT_RT* in mainline Linux
- The internals of *PREEMPT_RT*
- Interrupt handling: threaded interrupts, softirqs
- Locking primitives: mutexes and spinlocks, sleeping spinlocks
- Preemption models

Demo - Building a mainline Linux Kernel with the *PREEMPT_RT* patch

- Downloading the Linux Kernel, and applying the patch
- Configuring the Kernel
- Booting the Kernel on the target hardware

Lecture - Hardware configuration and limitations for Real-Time

- Interrupts and deep firmware
- Interaction with power management features: CPU frequency scaling and sleep states
- DMA

Half day 2

Lecture - Tools: Benchmarking, Stressing and Analyzing

- Benchmarking with *cyclictest*
- System stressing with *stress-ng* and *hackbench*
- The Linux Kernel tracing infrastructure
- Latency and scheduling analysis with *ftrace, kernelshark* or *LTTng*

Demo - Tools: Benchmarking, Stressing and Analyzing

- Usage of benchmarking and stress tools
- Common benchmarking techniques
- Benchmarking and configuring the hardware platform

Lecture - Kernel infrastructures and configuration

- Good practices when writing Linux kernel drivers
- Scheduling policies and priorities: *SCHED_FIFO*, *SCHED_RR*, *SCHED_DEADLINE*
- CPU and IRQ Affinity
- Memory management
- CPU isolation with *isolcpus*

Half day 3

Lecture - Real-Time Applications programming patterns

- POSIX real-time API
- Thread management and configuration
- Memory management: memory allocation and memory locking, stack
- Locking patterns: mutexes, priority inheritance
- Inter-Process Communication
- Signaling

Demo - Debugging a demo application

- Make a demo userspace application deterministic
- Use the tracing infrastructure to identify the cause of a latency
- Learn how to use the POSIX API to manage threads, locking and memory
- Learn how to use the CPU affinities and configure the scheduling policy

Questions and Answers

- Questions and answers with the audience about the course topics
- Extra presentations if time is left, according what most participants are interested in.